1 Synchrony affects Taylor's law in theory and data

Daniel C. Reuman^{a,b,c,*}, Lei Zhao^{a,b}, Lawrence W. Sheppard^{a,b}, Philip C. Reid^{d,e,f}, Joel E. Cohen^{c,g,h,*}
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^a Department of Ecology and Evolutionary Biology, University of Kansas, 1200 Sunnyside Ave., Lawrence, KS, 66045, USA

^b Kansas Biological Survey, University of Kansas, 2101 Constant Ave., Lawrence, KS, 66047, USA

^c Laboratory of Populations, Rockefeller University, 1230 York Ave, New York, NY, 10065, USA

^d The Laboratory, Sir Alister Hardy Foundation for Ocean Science, Citadel Hill, Plymouth PL1 2PB, UK

^e Plymouth University, Drake Circus, Plymouth PL4 8AA, UK

- ^f The Laboratory, Marine Biological Association of the UK, Citadel Hill, Plymouth PL1 2PB, UK
- ^g The Earth Institute and Department of Statistics, Columbia University, New York, NY 10027, USA
- 5 ^h Department of Statistics, University of Chicago, Chicago, IL 66037, USA
- 6 * Authors for correspondence: <u>reuman@ku.edu</u>, cohen@rockefeller.edu

7 Abstract

4

- 8 Taylor's law (TL) is a widely observed empirical pattern that relates the variances to the means of groups
- 9 of non-negative measurements via an approximate power law: variance_g $\approx a \times \text{mean}_g^b$, where g indexes
- 10 the group of measurements. When each group of measurements is distributed in space, the exponent b of
- 11 this power law is conjectured to reflect aggregation in the spatial distribution. TL has practical application
- 12 in many areas since its initial demonstrations for the population density of spatially distributed species in
- 13 population ecology. Another widely observed aspect of populations is spatial synchrony, which is the
- 14 tendency for time series of population densities measured in different locations to be correlated through
- time. Recent studies showed that patterns of population synchrony are changing, possibly as a
- 16 consequence of climate change. We use mathematical, numerical, and empirical approaches to show that
- synchrony affects the validity and parameters of TL. Greater synchrony typically decreases the exponent
 b of TL. Synchrony influenced TL in essentially all of our analytic, numerical, randomization-based, and
- empirical examples. Given the near ubiquity of synchrony in nature, it seems likely that synchrony
- influences the exponent of TL widely in ecologically and economically important systems.

21 Significance statement

- 22 Two widely confirmed patterns in ecology are Taylor's law (TL), which states that the variance of
- population density is approximately a power of mean population density; and population synchrony, the
- tendency of species' population sizes in different areas to be correlated through time. TL has been applied
- in many areas, including fisheries management, conservation, agriculture, finance, physics, and
- 26 meteorology. Synchrony of populations increases the likelihood of large-scale pest or disease outbreaks
- and shortages of resources. We show that changed synchrony modifies and can invalidate TL.
- 28 Widespread recent changes in synchrony, possibly resulting from climate change, may broadly affect TL
- 29 and its applications.
- 30 **body**

31 Introduction

- 32 Taylor's law (TL) is a widely observed empirical pattern that relates the variances to the means of groups
- of measurements of population densities or other non-negative quantities via a power law: variance_g = a
- 34 × mean_g^b, where g indexes the groups of measurements, a > 0, b is usually positive, and a and b are both
- independent of g. Equivalently, $log(variance_g) = b \times log(mean_g) + log(a)$. The parameter b has the same
- numerical value whether it appears as the exponent of the power law or as the slope of the linear relation
- between $log(variance_g)$ and $log(mean_g)$. Thus b may be referred to as the exponent or the slope of TL.
- 38 TL has been verified in data on the population sizes and population densities of hundreds of taxa,
- including aphids (1), crops (2), fish (3, 4), birds (5), and humans (6). TL has also been discovered in

- 40 many other non-negative measurements (7), including recently tornados per outbreak (8) and stocks (9).
- In physics, TL is sometimes called "fluctuation scaling". TL has been generalized (10), and applied to or 41
- proposed for application to fisheries management (3, 4), estimation of species persistence times (11), and 42
- 43 agriculture (2, 12, 13). Potential mechanisms of TL have been explored extensively (e.g., 9, 14, 15).
- Because of its ubiquity, it has been suggested that TL could be another "universal law," like the central 44 45 limit theorem (16).
- There are multiple versions of TL. "Temporal TL" and "spatial TL," on which we focus, use time 46 47 series, $Y_i(t)$, of population densities measured in locations i = 1, ..., n at times t = 1, ..., T. For temporal TL, the groups, g, consist of all measurements made in a location, i (means and variances are computed 48 49 over time). For spatial TL, groups are measurements at a single time, t (means and variances are over 50 space).
- 51 Synchrony (metapopulation synchrony, spatial synchrony) is another ubiquitous and fundamental 52 ecological phenomenon. It is the tendency for time series of population densities of the same species 53 measured in geographically separated locations to be correlated through time. It has been observed in 54 organisms as diverse as protists (17), insects (18), mammals (19, 20) and birds ((21); see also (22) for 55 many other examples). It relates to large-scale pest or disease outbreaks and shortages of resources (23, 56 24), and has implications for conservation because populations are at greater risk of simultaneous 57 extinction if they are simultaneously rare (24).
- 58 Although some empirical and theoretical connections have been made between synchrony and TL 59 (7, 14, 20, 25), the connections are far from completely understood, and do not encompass all versions of 60 TL. Synchrony, like TL, may reflect aggregation because the spatial extent of correlations among population time series indicates the geographic size of outbreaks (26). Engen, Lande and Saether (25) 61 62 connected TL with synchrony theoretically, but did not use spatial or temporal TL. Temporal TL has been 63 related to a kind of synchrony that occurs on spatial scales smaller than that of sampling (7, 14).
- 64 The "Moran effect" refers to synchrony caused by synchronous environmental drivers. Changes 65 in Moran effects as a consequence of climate change may alter synchrony. Long-term increases in the synchrony of caribou populations in Greenland were associated with increases in the synchrony of 66 67 environmental drivers in the area, apparently through modified Moran effects (19). The latter were in turn linked to global warming. Similar associations held for North American bird species (21). Large-scale 68 climatic changes in the North Atlantic Oscillation caused changes in winter temperature synchrony, which 69 70 in turn caused changes in the synchrony of pest aphid species in the UK (27). Changes in the synchrony 71 of plankton (26) and tree rings (28) have been associated with climate change. If synchrony influences 72 TL, then changes in synchrony may change TL in ecologically and economically important systems.
- 73 We analyze connections between synchrony and spatial TL to answer the following questions. Do 74 the presence and strength of synchrony in population time series influence whether TL holds, and if so, 75 how? Do the presence and strength of synchrony influence the slope b of TL, and if so, how? Because of 76 the fundamental importance of both TL and synchrony to population ecology, illuminating connections 77 between these phenomena is of intrinsic interest, but we are also motivated by the applied importance of 78 TL and by concern that climate change may modify synchrony.

79 **Results**

80 Analytic results

- 81 Suppose the population size or density in location *i* at time *t* is modeled by the non-negative random
- 82 variable $Y_i(t)$, for $i=1,\ldots,n$. Assume that the multi-variate stochastic process $Y(t) = (Y_1(t),\ldots,Y_n(t))$ is
- stationary and ergodic (29); these are standard assumptions (SI Appendix S1). We use the standard spatial 83
- sample mean and sample variance: $m(t) = \frac{1}{n} \sum_{i=1}^{n} Y_i(t)$ and $v(t) = \frac{1}{n-1} \sum_{i=1}^{n} Y_i(t)^2 \frac{n}{n-1} m(t)^2$. The traditional plot to test spatial TL is the log(v(t))-versus-log(m(t)) scatter plot for a finite realization of 84
- 85
- these processes. TL hypothesizes that this plot will be approximately linear. The linear regression slope is 86
- $b_t = \frac{\text{cov}_t(\ln(m(t)),\ln(v(t)))}{\text{var}_t(\ln(m(t)))}$ (30). The subscripts *t* indicate that the variance var_t and the covariance cov_t are 87

- computed across time for the finite realization, while each value of m(t) and v(t) is computed across space
- 89 at time t. A standard (22) measure of average synchrony, $\Omega_t = \frac{1}{n^2} \sum_{i,j=1}^n \operatorname{cor}_t(Y_i(t), Y_j(t))$, averages the
- 90 temporal correlations of every pair of population-dynamic time series. This summation includes the terms
- 91 with i = j, which equal 1, and hence Ω_t is 1/n when the correlations with $i \neq j$ are 0. Ω_t is 0 when the
- 92 spatial-average time series is constant, and Ω_t cannot be negative (SI Appendix S1). We are interested in
- how Ω_t may affect whether the relationship between the log-mean and the log-variance is linear, and the value of the slope b_t when linearity holds. For long time series, it suffices (SI Appendix S1) to consider
- 94 value of the slope b_t when linearity holds. For long time series, it suffices (SI Appendix S1) to consider 95 the population quantities $b = \frac{\operatorname{cov}(\ln(m),\ln(v))}{\operatorname{var}(\ln(m))}$ and $\Omega = \frac{1}{n^2} \sum_{i,j=1}^{n} \operatorname{cor}(Y_i, Y_j)$, assuming all the expectations,
- 96 variances and covariances in these and other expressions exist (details in SI Appendix). Thus we work
- 97 with the time-independent distribution $Y=(Y_1, ..., Y_n)$. Autocorrelation in time series will not influence the
- 98 relationships we study if time series are long enough for empirical and true marginal distributions to be
- 99 similar (SI Appendix S1).

100 Applying the delta method (31),
$$\ln(m) \approx \ln(E(m)) + \frac{m - E(m)}{E(m)}$$
, $\ln(v) \approx \ln(E(v)) + \frac{v - E(v)}{E(v)}$, and

101
$$\operatorname{var}(\ln(m)) \approx \frac{\operatorname{var}(m)}{\operatorname{E}(m)^2}$$
, so (SI Appendix S1)

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$$b \approx \frac{(n-1)E(m)}{n} \frac{\operatorname{cov}(m,v)}{(A-\operatorname{var}(m))\operatorname{var}(m)},$$
 (Eq. 1)

103 where the first factor in this expression and the quantity $A = \frac{1}{n} \sum_{i=1}^{n} E(Y_i^2) - E(m)^2$ depend solely on the 104 marginal distributions, Y_i , and not on the correlations, $cor(Y_i, Y_j)$. On the other hand, var(m) equals 105 $\frac{1}{n^2} \sum_{i,j=1}^{n} cov(Y_i, Y_j)$, which relates to synchrony, Ω , and is similar in form. Eq. 1 therefore provides the 106 intuition behind our subsequent analyses: if synchrony (Ω or var(m)) changes and the marginals, Y_i , 107 remain fixed, then one expects the slope *b* to change. The following theorem supports this intuition. 108 **Theorem.** Suppose Y_i are identically distributed (but not necessarily independent) with $E(Y_i) = M > 0$

and finite var $(Y_i) = V > 0$. Assume $\mu_{ij} = E((Y_i - M)(Y_j - M)), \mu_{ijk} = E((Y_i - M)(Y_j - M)(Y_k - M))$

 $\begin{array}{c} \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{j} - M)), \mu_{ijk} = E((i_{i} - M)(i_{j} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{j} - M)), \mu_{ijk} = E((i_{i} - M)(i_{j} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{j} - M)), \mu_{ijk} = E((i_{i} - M)(i_{j} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{j} - M)), \mu_{ijk} = E((i_{i} - M)(i_{j} - M)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{j} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{j} - M)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{j} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{j} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = v > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = u > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = u > 0. \text{ Assume } \mu_{ij} = E((i_{i} - M)(i_{k} - E)) \\ \text{and nime var}(i_{i}) = u > 0. \text{ Assume } \mu_{ij} = u > 0. \text{ Assume } \mu_{i} = u > 0. \text{ Assume } \mu_{i} = u > 0. \text{ Assume$

110 *M*), and $\mu_{ijkl} = E((Y_i - M)(Y_j - M)(Y_k - M)(Y_l - M))$ are finite for all *i*, *j*, *k*, *l*, and define $\rho_{ij} =$ 111 $\operatorname{cor}(Y_i, Y_j) = \frac{\mu_{ij}}{V_i}$ and $\rho_{ijk} = \frac{\mu_{ijk}}{W_i}$. Then

$$b \approx \left(\frac{M\mu_{iii}}{V^2}\right) \left(\frac{\sum_{i,j=1}^n \rho_{ijj} - \frac{1}{n} \sum_{i,j,k=1}^n \rho_{ijk}}{n^2 (1-\Omega)\Omega}\right).$$
 (Eq. 2)

113 The approximation is better whenever the coefficients of variation of the sample mean $\frac{\sqrt{\text{var}(m)}}{E(m)} = \frac{\sqrt{V\Omega}}{M}$ and

114 sample variance $\frac{\sqrt{\text{var}(v)}}{E(v)}$ are smaller, and is asymptotically perfect as these quantities approach 0.

115 Additional details, alternative mathematically equivalent expressions for b, and a proof of the theorem are 116 in SI Appendix S2.

- 117 This theorem extends a theorem of Cohen and Xu (15) which assumes that the Y_i are independent 118 and identically distributed (iid). In that case, the second factor on the right of Eq. 2 is 1 and $b \approx \left(\frac{M\mu_{iii}}{V^2}\right)$, 119 which equals the skewness $\frac{\mu_{iii}}{V^{3/2}}$ of Y_i divided by its coefficient of variation $V^{1/2}/M$. Independence of the
- 120 Y_i is not necessary here: the same formula holds if $\rho_{ij} = 0$ for $i \neq j$ and $\rho_{ijk} = 0$ whenever i, j, and k are
- not all equal. Cohen and Xu (15) concluded that, in the iid case, skewness of Y_i is necessary and sufficient
- for TL to have slope $b \neq 0$. Our theorem extends this result to the case of identically distributed Y_i that
- 123 may be non-independent.
- 124 The denominator $n^2(1 \Omega)\Omega$ in Eq. 2 is a \cap -shaped function of Ω (i.e., it increases, has a 125 maximum and then decreases again as Ω increases). So Eq. 2 may seem to suggest that *b* is a U-shaped 126 function of synchrony (it decreases, has a minimum, and then increases again). But the numerator of the 127 second factor of Eq. 2 may, *a priori*, also be a \cap -shaped function of synchrony, so a U-shaped

- dependence of *b* on synchrony is not mathematically certain, nor are any of the components of such a
- 129 dependence (the initial decrease, and the internal minimum and subsequent increase of b as Ω increases).
- 130 Dependence of the numerator of Eq. 2 on Ω also means $\lim_{\Omega \to 0} b$ and $\lim_{\Omega \to 1} b$ can be finite even though
- 131 $\lim_{\Omega \to 0} (1 \Omega)\Omega$ and $\lim_{\Omega \to 1} (1 \Omega)\Omega$ are 0.
- 132 Numeric results

To illustrate the identically distributed case, we performed numerical simulations based on multivariate 133 normal random variables $X = (X_1, ..., X_n)$ with mean (0, ..., 0) and covariance matrix with diagonal 134 entries 1 and off-diagonal entries equal to a parameter, $\rho \ge 0$. We let $Y_i = \varphi(X_i)$, where the 135 transformations $\varphi(.)$ were chosen, in different simulations, to make the Y_i a variety of Poisson, negative 136 137 binomial, gamma, exponential, chi-squared, normal and log-normal distributions. Increases in ρ produced 138 increases in Ω . Exponential and chi-squared distributions are special cases of gamma distributions. We produced separate results for these distributions because they are widely used. Results are in SI Appendix 139 140 S3; fig. 1 shows typical results for Poisson and gamma examples.

141 Results generally agreed with the above intuitions and analyses. The linearity hypothesis of TL was usually, but not always, an adequate approximation in that linearity and homoscedasticity could not 142 143 be rejected statistically (SI Appendix S6 for details on how this was tested). In agreement with our theorem and Cohen and Xu (15), when a shifted normal distribution (which has skewness 0) was used for 144 145 Y_i , b was approximately 0 for all values of Ω . For skewed distributions, the slope b was generally smaller for larger values of Ω , confirming the prediction that b depends on synchrony. Although b decreased 146 147 steeply as Ω increased from 0 for all skewed distributions, b most commonly continued to decrease monotonically as Ω increased further, even for large values of Ω , except for a few cases using gamma 148 distributions, for which modest increases were observed (SI Appendix figs S14-S20): the *b*-versus-149 150 synchrony relationship was only occasionally U-shaped, and then only mildly so. The right side of Eq. 2 151 was computed analytically (i.e., with formulas) for gamma, exponential, chi-squared, normal, and lognormal examples, and the formulas were compared with numerical results. For some distributions and 152 153 parameters, the approximation was very accurate, and it was always at least qualitatively accurate (in the 154 sense that it showed similar declines of b with increasing synchrony), except for the log-normal 155 distribution, for which it was very inaccurate for some parameters, due to insufficient sampling, as 156 previously observed (15). As expected from the theorem, Eq. 2 was a better approximation for smaller Ω .

157 We also constructed non-identically distributed examples by applying transformations to 158 multivariate normal random variables. Our theorem, which assumed identically distributed Y_i , did not 159 apply here. The random variable X was the same as above and $Y_i = \varphi_i(X_i)$ where the $\varphi_i(.)$ differed for 160 different *i*. The $\varphi_i(.)$ were chosen so that all the Y_i were from the same family (Poisson, negative binomial, 161 gamma, exponential, chi-squared, normal or log-normal), though with different parameters. For gamma, normal, exponential, and log-normal examples, the $\varphi_i(.)$ were chosen so that Y_i was distributed in the same 162 way as (but was not equal to) $f_i Y_1$, where $0 < f_1 < ... < f_n$. This procedure was not possible for negative 163 binomial, Poisson, or chi-squared distributions because these families are not closed under multiplication 164 by positive real numbers. Distributions used for these families and the results are described in SI 165 166 Appendix S4.

167 Results reinforced most of the generalities that emerged from the above analytical results and simulations, although a U-shaped dependence of b on Ω was more common and stronger in these 168 examples (SI Appendix S4). Exceptions to general tendencies did occur. For gamma, exponential, normal, 169 170 and log-normal examples, TL was usually a good approximation. Although linearity was often 171 statistically rejected, departures from linearity were modest: log(v)-versus-log(m) plots stayed very close to the regression line. The slope b always showed an initial steep decrease as Ω increased from 0 for all 172 173 gamma, exponential, normal, and log-normal examples. As $\Omega \rightarrow 1$, these examples approached the case for which Y_i equals $f_i Y_1$ almost surely in addition to having the same distribution as $f_i Y_1$. In that limit, m =174 $\operatorname{mean}_i(Y_i) = \operatorname{mean}_i(f_iY_1) = Y_1 \operatorname{mean}_i(f_i)$, whereas $v = \operatorname{var}_i(Y_i) = \operatorname{var}_i(f_iY_1) = Y_1^2 \operatorname{var}_i(f_i)$. Therefore 175 TL should hold exactly with slope 2. This argument holds even for symmetric distributions like the 176

177 normal. Our numeric simulations confirmed that as Ω increased toward 1, root mean squared errors from

- 178 $\log(v)$ -versus- $\log(m)$ regressions went to 0 and b went to 2, sometimes from above and sometimes from
- below. An approach from below was paired with U-shaped dependence of b on Ω , which was common and often pronounced in these examples. The earlier result (15) that skewness is required for TL to have
- slope $b \neq 0$ if Y_i are identically distributed does not hold when Y_i are not identically distributed:
- simulations with Y_i normally distributed had $b \neq 0$ (SI Appendix figs S45-S50). For Poisson and chi-
- 183 squared examples. TL was usually a reasonable approximation, and b declined steeply as Ω increased
- from 0 and continued to decrease for larger Ω . Negative binomial examples often strongly violated TL,
- 185 especially for large values of Ω (e.g., SI Appendix figs S63, S64). Nonetheless, the slope *b* tended to 186 decrease with increasing Ω whenever linearity held approximately.
- Another way to create families of random variables Y with fixed marginal distributions but 187 188 varying synchrony is based on sums of independent random variables representing local and regional 189 influences on populations (32). It is well known that for independent Poisson random variables X and X_i , 190 the sum $X+X_i$ is Poisson distributed. Similar facts are also true for the negative binomial, gamma, and 191 normal families. Therefore Y was generated by setting $Y_i = X + X_i$ for independent X and X_i for i = 1, ..., n. 192 The variable X can be interpreted as the influence of a large-spatial-scale environmental or other factor 193 that affects all populations; the X_i are local effects. Different relative variances of X and the X_i led to 194 different amounts of correlation (synchrony) among the Y_i . By this approach, we constructed Y such that 195 the Y_i were identically distributed according to a desired Poisson, negative binomial, gamma, exponential, chi-squared, or normal distribution, with a desired level of synchrony among the Y_i . Details of this 196 construction and the results are in SI Appendix S5. 197
- 198 Results were the same in some respects as the results above, and differed in others. Larger values 199 of synchrony always decreased the slope b (except for normal Y_i , for which b was always 0, as expected 200 from the theorem since Y_i are again identically distributed). The slope b went to 0 as Ω approached 1. The approximation Eq. 2 applied reasonably accurately. In all cases, the right side of Eq. 2 reduced to simple, 201 202 monotonically decreasing functions of Ω . However, contrary to prior simulations, $\log(v)$ -versus- $\log(m)$ plots often strongly violated the linear hypothesis of TL. Values of synchrony Ω larger than 0 smeared 203 204 points rightward in log(v)-versus-log(m) space, destroying the linear relation expected from TL. This 205 smearing decreased b, but also changed its meaning from representing the slope of a linear pattern to 206 representing the slope of a linear approximation to a nonlinear pattern. The decrease in b did not reflect 207 maintenance of a linear pattern with a changed slope, as in prior examples (fig. 1, SI Appendices S3-S4). 208 SI Appendix S5 gives an explanation for this effect.

209 Empirical results

- 210 We examined the influence of synchrony on empirical data using 82 spatiotemporal population data sets.
- The datasets included annual time series of population density for 20 species of aphid sampled for 35
- 212 years in 11 locations across the UK, annual density time series for 22 plankton groups sampled in 26
- regions in the seas around the UK for 56 years, and chlorophyll-*a* density time series measured at several
- 214 locations at each of 10 depths in four distance categories from the coast of Southern California over 28
- 215 years. We henceforth refer to distance categories from shore in the chlorophyll-*a* data as groups 1-4,
- where 1 refers to the closest category to shore, and larger group numbers correspond to farther categories
- from shore. See Methods for further descriptions of the data and their processing.
- The spatial TL was reasonably well supported by all 82 datasets. SI Appendix figs. S91-S96 plot $\log(v)$ versus $\log(m)$ and give statistical tests of TL. Conformity to TL was not perfect, but was quite good
- overall, except for the chlorophyll-*a* data in group 3 (SI Appendix fig. S95). Linearity or
- homoskedasticity of the log(v) versus log(m) relationship was rejected at the 1% level for 7 of 82 data sets (1 aphid species; 1 depth from group 1; 5 depths from group 3).
- 222 (1 april species; 1 depin from group 1; 5 depins from group 5).
- 223 We examined correlations across species, taxonomic groups, or depths (for the aphid, plankton,
- and chlorophyll-*a* data sets, respectively) between measurements of *b* and Ω . Factors other than
- synchrony may have influenced these results and are accounted for below after examining the raw
- 226 correlations here. Fig. 2 (left panels) shows that b and Ω were significantly negatively correlated across

227 aphid species, and across depths in the chlorophyll-*a* data, groups 1 and 2, and were non-significantly 228 negatively correlated across plankton groups in the plankton data. Higher synchrony Ω was associated 229 with lower slope *b* in these data, despite possible confounding influences.

However, significant positive correlations occurred in the chlorophyll-*a* data, groups 3 and 4 (fig. 2m, p). These positive associations appear to conflict with simulation results, which generally support a negative association between *b* and Ω , unless confounding factors overwhelmed a negative influence of synchrony on *b* in these data. For instance, changes across depths in *b* may be influenced for the chlorophyll-*a* data, groups 3 and 4, by changes across depths in Ω and by possible changes in time series marginal distributions. Simulations carried out above held time series marginal distributions constant when synchrony was varied.

237 To control for changes in time series marginal distributions that may have occurred in concert 238 with changes in synchrony, we decomposed slopes $b = b_{marg} + b_{sync}$ into contributions due to synchrony, 239 b_{sync} , and due to time series marginals, b_{marg} , to separate influences of synchrony and time series marginal distributions on the slope b. We computed the marginal contribution, b_{marg} , by independently randomizing 240 time series and then re-computing the log(v)-versus-log(m) slope (Methods) to eliminate synchrony and 241 ensure that it cannot contribute to $b_{\text{marg.}}$. Then we defined b_{sync} as $b - b_{\text{marg.}}$. Fig. 2 (right panels) shows that 242 b_{sync} was negatively associated with Ω in all cases (albeit not always significantly), even for chlorophyll-a 243 244 data, groups 3 and 4 (fig. 20, r). For these groups, b_{marg} was strongly positively associated with Ω (fig. 2n, q). This positive association overwhelmed the negative association of b_{sync} with Ω to produce the overall 245 246 positive association of b with Ω observed in fig. 2m, p. Thus group 3 and 4 results did not conflict with 247 simulation results, but rather showed that other factors dominated. The change in time series marginal 248 distributions for the chlorophyll-a data was not surprising because these data were gathered across 249 different depths, and chlorophyll-a density varies with depth in the ocean. SI Appendix fig. S99 is like 250 fig. 2, but identifies the species/groups/depths of plotted points; panels for the chlorophyll-a data show that depth probably played a role. Differing thermocline depths across groups 1-4 (SI Appendix fig. S101) 251 252 may also have been important.

253 To examine in more detail the influence of synchrony on spatial TL in empirical data, we 254 performed further randomizations (Methods). Randomizations reduced or increased the synchrony in each 255 of our 82 spatiotemporal population data sets while not modifying the marginal distributions in each sampling location. In virtually every case, increasing synchrony decreased b, while decreasing synchrony 256 257 increased b (fig. 3). The strength of the effect varied across data sets and was typically steeper for smaller 258 values of synchrony. Values of b_{marg} correspond to the y-axis intercepts of the curves in fig. 3. In a few 259 cases, b appeared to depend in a U-shaped way on synchrony, as in some simulations, but the U shape was modest when it occurred, also in agreement with simulations (i.e., only modest increases in b with 260 increasing Ω were observed on the right portions of plots in fig. 3). The linearity of TL was approximately 261 262 supported across the range of synchrony values except possibly for the highest synchrony values and the chlorophyll-a data in group 3 (SI Appendix figs S97, S98). 263

All results are summarized, with hyperlinks to supporting figures and derivations, in SI Appendix tables S3-S4.

266 Discussion

Understanding the relationship of synchrony with TL is important because both patterns are widespread in
population ecology, and because TL and recent observed climate-change-induced modifications in
synchrony have applied importance (19, 21, 26-28).

270 We showed that the strength of synchrony substantially influences the log(variance)-versus-

log(mean) scatter plot, of which TL is one special form. It can destroy linearity of TL, but more

272 commonly it preserves linearity and changes the slope b of the plot. Synchrony influenced the slope of TL

in essentially all of our analytic, numeric, empirical, and randomization-based examples. The one

systematic exception occurred when the marginal distributions of time series in different locations were
 normally and identically distributed so that a nonzero-slope of TL was not expected with or without

- 275 normally and identically distributed so that a nonzero-slope of TL was not expected with or without
 276 synchrony (15). As synchrony increased from 0, slope *b* almost always decreased guite sharply. For some
 - 6

theoretical and randomization examples, increasing synchrony starting from higher levels of synchrony
increased the slope *b* modestly, but analogous increases were not seen in empirical examples when
confounding changes in time-series marginal distributions were controlled. Our analytic results generalize
a theorem of Cohen and Xu (15). We provided a simple method of decomposing *b* into its contributions
due to synchrony, *b*_{sync}, and due to time-series marginal distributions, *b*_{marg}.

282 Ballantyne and Kerkhoff (14) and Eisler, Bartos and Kertesz (7) (their section 3) described 283 interesting links between small-spatial-scale synchrony and temporal TL. To explain the basic idea, we 284 construct an idealized example using aphids monitored by suction traps. Suppose trap i for i = 1, ..., n has 285 A_i agricultural fields that can produce aphids within its sampling range. Suppose traps are placed so that no fields contribute to more than one trap. Suppose field ij ($i = 1, ..., n, j = 1, ..., A_i$) contributes a random 286 287 variable $V_{ii}(t)$ to trap i in year t, and suppose all the $V_{ii}(t)$ are identically distributed with mean μ and 288 variance σ^2 . Then if, for fixed i, $V_{ii}(t)$ are perfectly correlated so that all fields near i produce the same number of sampled aphids per year (this is very strong small-spatial-scale synchrony, the spatial scale 289 290 being smaller than the spatial resolution of sampling), the mean of the number of aphids $\sum_i V_{ii}(t)$ sampled by trap *i* in year *t* is $\mu_i = A_i \times \mu$, and the variance is $\sigma_i^2 = A_i^2 \times \sigma^2$. Assuming random variables for 291 different times t are independent, the mean and variance across time of numbers of aphids sampled by 292 293 trap i will converge almost surely, in the limit of long time series, to these same values (strong law of large numbers). Log transforming and doing basic algebra gives $\ln(\sigma_i^2) = 2 \times \ln(\mu_i) + C_1$ for a constant C_1 ; 294 this is a temporal TL with slope 2. If, for fixed i, $V_{ii}(t)$ are independent, then the mean of $\sum_i V_{ii}(t)$ is 295 again $\mu_i = A_i \times \mu$, but the variance is now $\sigma_i^2 = A_i \times \sigma^2$. Log transforming and doing basic algebra gives 296 297 temporal TL with slope 1. (This example shows, incidentally, that observing TL with slope 1 need not be 298 evidence that the aphids or other organisms are Poisson-distributed, even though Poisson-distributed 299 aphids or other organisms lead to TL with slope 1.)

The above example differs in at least two important ways from our results. First, it concerns
 temporal TL, whereas we studied spatial TL. Second, the above example concerns synchrony at a
 different spatial scale from our study. Although dependence between numbers of aphids sampled at
 different traps seems likely to imply dependence between numbers contributed by fields within the range
 of individual traps, the reverse need not be true.

It seems worthwhile, in future research, to examine the possibly complex relationships between the above example (7, 14) and our study. While Eisler, Bartos and Kertesz (7) focus on temporal TL, they state without proof or details that many of their results also apply to TL more generally. Relationships between spatial and temporal TL have recently been examined (20) and may help connect the TL in the above example to the spatial TL of our study. Perhaps all these versions of TL could be formally related to each other and to synchrony.

Engen, Lande and Saether (25) produced a general model for analyzing a version of TL in which 311 each group of measurements of population density comes from plots of the same size, but different groups 312 use different plot sizes (distinct from spatial and temporal TL). On p. 2620 they remind the reader that 313 increasing population migration leads to increasing synchrony, which causes "the slope [of this version of 314 315 TL] ... to increase from 1 to 2 ... as the migration increases." Engen, Lande and Saether (25) seem to indicate in the final sentences of their paper that their model could be extended to address spatial TL, 316 317 possibly helping to illuminate connections among spatial, temporal, and their versions of TL and 318 synchrony.

319 Cohen and Saitoh (20) examined relationships among synchrony and spatial and temporal TL in 320 voles. Their example is consistent with our work and illustrates the value of our general results for understanding TL in specific systems. Using 31 years of population density data for the grey-sided vole, 321 Myodes rufocanus, at 85 locations in Hokkaido, Japan, Cohen and Saitoh (20) verified that spatial and 322 323 temporal TL held for the data, as well as for simulations of a previously validated Gompertz model of the dynamics of these populations. However, simulated time series had spatial and temporal TL slopes 324 325 substantially steeper than those from data. Cohen and Saitoh (20) observed that most pairs of vole populations were significantly temporally correlated, and modified the Gompertz model accordingly. 326

- 327 When density-independent perturbations in model dynamics were synchronized, inducing synchrony in
- 328 simulated population time series, and when simulated populations with higher mean density had a
- reduced variance of density-independent perturbations, the modeled slopes of spatial and temporal TL
- were reduced to values similar to those of the data. Our results here account qualitatively for the effect on
- TL slopes of the first of these two modifications of the Gompertz model, i.e., the introduction ofsynchrony.
- Our theoretical models and our randomizations kept the marginal distributions of time series fixed as synchrony changed, to exclude confounding factors. In our empirical analyses, we separated the contribution of synchrony, b_{sync} , to the empirical TL slope *b*. In reality, synchrony may change jointly with marginal distributions across species, or depths, or some other axis of variation, as in some of our empirical data (fig. 2). Covariation between changes in b_{sync} and b_{marg} should be context dependent, may be biologically revealing, and is worth examining when multiple values of *b* are computed.
- Increasing evidence shows that Moran effects, possibly due to climate change, modify synchrony
 (19, 21, 26-28). The present work indicates that changed synchrony will modify the slope and possibly
 the validity of TL, with ramifications for applications of TL in many areas including resource
- the validity of 1L, with ramifications for applications of 1L in many areas including resource
- management (3), conservation (11), human demography (6), tornado outbreaks (8), and agriculture (2, 12,
- 343 13). Given the ubiquity of synchrony in nature (22), it seems highly likely that synchrony often affects
 344 values of TL slopes in real populations, as Hokkaido voles showed. It is important to understand better
- 345 how TL is affected by synchrony and other factors.

346 Methods

- 347 *Analytic and numeric methods*
- Full details of analytic results are in SI Appendix S1-S2, and full details of numeric simulations are in SI
- Appendix S3-S6.
- 350 *Data*.
- Rothamsted Insect Survey (RIS) runs a network of suction traps that sample flying aphids. Daily aphid
- counts are collected throughout the flight season for many species at multiple locations. Data were
- processed to produce annual total counts for 20 species (SI Appendix table S1) at 11 locations (SI
- Appendix table S2) for the years 1976 through 2010, forming 20 spatiotemporal population datasets.
- The Continuous Plankton Recorder (CPR) survey, now operated by the Sir Alister Hardy Foundation for Ocean Science (SAHFOS), has sampled the seas around the UK for plankton abundances since before World War II, using a sampling device towed behind commercial ships. Data were processed to produce annual abundance time series for 22 phytoplankton and zooplankton taxa (SI Appendix table S1) for $26 \ 2^{\circ} \times 2^{\circ}$ areas around the UK for the years 1958 through 2013, forming 22 spatiotemporal
- 360 population datasets.
- The California Cooperative Oceanic Fisheries Investigations (CalCOFI) has surveyed the California Current System since 1949 measuring chlorophyll-*a* regularly since 1984. Time series of spring chlorophyll-*a* were based on measurements at 55 sites which were divided into four groups based on distance from shore, with group 1 near to shore (average 87.7 km) and group 4 far from shore (average 539.3 km). For each site and sampling occasion, annual chlorophyll abundances were calculated for 0, 10, 20, 30, 50, 75, 100, 125, 150, and 200 m depths, forming 10 spatiotemporal datasets for each group.
- 367 Further data details are in SI Appendix S7.

368 Randomizations and the decomposition of b

- 369 Given an $T \times n$ matrix with each column containing a time series of population size or density from one
- 370 location (so T is the length of time series and n is the number of sampling locations), synchrony was
- 371 reduced without affecting time series marginal distributions for the sampling locations by selecting k rows
- randomly, and then randomly replacing the entries in those rows with randomly chosen (with
- replacement) values from the same column; this replacement was done independently within each
- $\frac{374}{1000}$ column. Larger values of *k* destroy a larger fraction of any synchrony that was originally present in the
- time series. Setting k = T completely eliminates synchrony by randomizing each complete time series

- independently. To increase the synchrony, starting from the original time series, *k* rows were again
- selected randomly. Within each column of this $k \times n$ submatrix separately, entries were sorted into
- increasing order. For each value of k, k rows were selected randomly in 100 ways, with values of b and Ω
- averaged for fig. 3. The value b_{marg} was computed by randomizing time series with k = T as described above to destroy synchrony, and then computing h = h for the rendemized detect
- above, to destroy synchrony, and then computing $b = b_{marg}$ for the randomized dataset.

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452		

454 Figure Legends

- **Figure 1.** Effects of spatial synchrony on spatial Taylor's law (TL) for a model with populations
- 456 identically distributed in different sampling locations and identically distributed and independent (iid)
- through time at each location. Examples use Poisson (a; $\lambda=5$) and gamma (b; shape $\alpha=8$, rate $\beta=2$)
- 458 distributions (see SI Appendix S3 for parameterization of the gamma distribution). Top panels: *m* is 459 spatial sample mean and *v* is spatial sample variance. Confirming TL visually, approximately linear
- 460 $\log_{10}(v)$ -versus- $\log_{10}(m)$ relationships held with selected values of ρ . Slopes were shallower for greater
- 461 synchrony. Middle panels: TL had a shallower slope for greater synchrony. Black lines show the average
- 462 (across the 50 simulations) TL slope plotted against average synchrony (error bars are standard
- deviations), and average root mean squared deviations of $\log_{10}(v)$ values from $\log_{10}(v)$ -versus- $\log_{10}(m)$
- linear regressions; red lines (b) are analytic approximations (Eq. 2, theorem 5 of SI Appendix S2.3),
 computable with readily available software for continuous distributions (SI Appendix S3), with + and ×
- 466 symbols respectively indicating points for which approximations were deemed adequate via two different
- 467 methods, both symbols plotted when both methods indicate an adequate approximation. Each simulation
- 468 consisted of 25 populations sampled 100 times each. Bottom panels: fractions of *m* and *v* values which
- 469 were 0 and therefore ignored; and fractions of 50 simulations for which statistical tests rejected linearity
- 470 or homoskedasticity of the $\log_{10}(v)$ -versus- $\log_{10}(m)$ relationship with 95% confidence. See SI Appendix
- figs. S1-S32 for other parameters and distributions, which often showed similar patterns. See SI Appendix
- 472 S3 and S6 for additional details.
- 473

Figure 2. Plots of TL slope *b* against synchrony Ω for 20 species of aphid in the UK (a), 22 plankton groups in the seas around the UK (d), and chlorophyll-*a* density time series measured at 10 depths in groups 1-4 (g, j, m, p; Methods), which are distance categories from shore. Panels are paired with contributions to the slope, *b*, of marginal-distribution structure (b_{marg} ; b,e,h,k,n,q) and synchrony (b_{sync} ; c,f,i,l,o,r; Methods). Associations between synchrony and TL slope *b* (left panels) can be due to associations between synchrony and b_{marg} or b_{sync} or both, since $b = b_{marg} + b_{sync}$. SI Appendix fig. S99 shows another version of the figure that labels individual species/groups/depths.

481

Figure 3. The dependence of the spatial TL slope *b* on synchrony Ω , where synchrony was manipulated

through randomizations or sorting of time series (Methods), for aphid species (a), plankton groups (b),
and a chlorophyll-*a* density index measured at 10 depths (c-f). Panel c is for the 19 group-1 locations,

484 and a chorophyn-a density index measured at 10 depins (c-1). Panel c is for the 19 group-1 locations, 485 panel f is for the 12 group-4 locations, and panels d and e are for 12 locations in each of two intermediate

- 486 distance categories (groups 2, 3; Methods). Red points on plotted lines correspond to individual,
- 487 unrandomized aphid species (a), plankton groups (b), and sampling depths (c-f), detailed in SI Appendix
- table S1. Grey points are averages over randomizations or sortings (Methods). Values for individual
- 489 randomizations are shown in SI Appendix fig. S100.